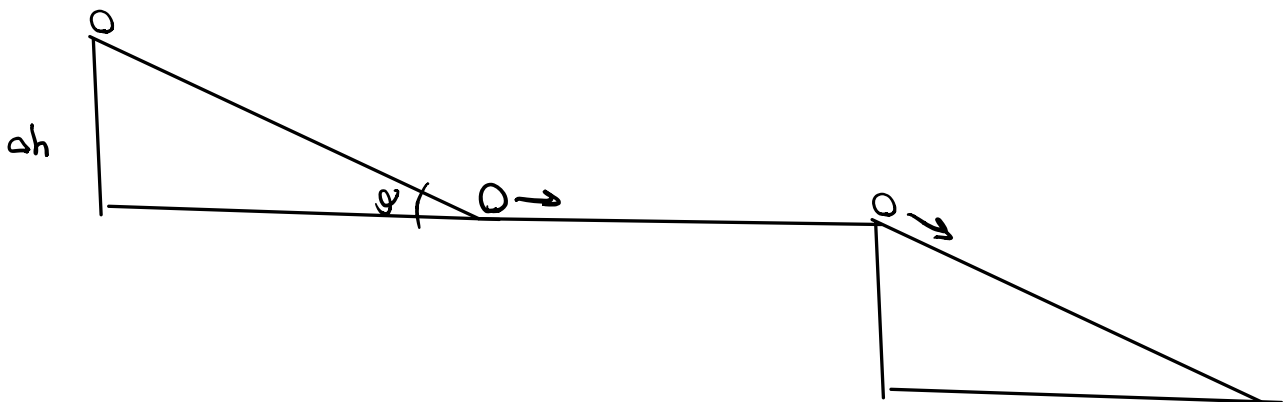
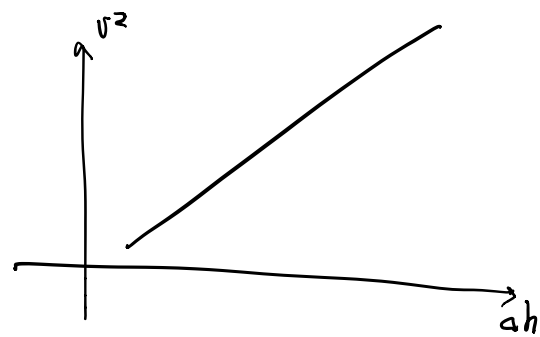
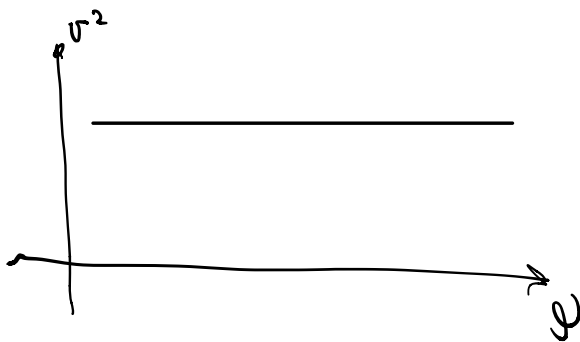
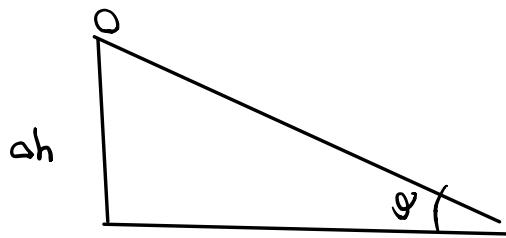
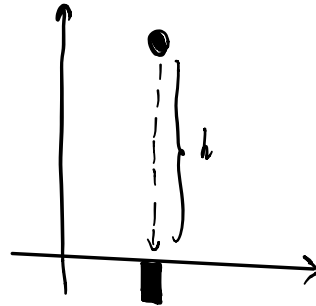


$\frac{1}{2} m v^2$  vs.  $F \times h$

a logica

BATTIPAZO



$$\sigma_{i,f}^2 = k \cdot \Delta h$$

$$\sigma_{2,f}^2 = v_{i,f}^2 + k \Delta h$$

$$U = k h \sim m v^2$$

$$\begin{aligned} [k] &= \left[ \frac{m v^2}{h} \right] = [k_g] \left( \frac{m}{s} \right)^2 \frac{1}{[m]} \\ &= [k_g] \frac{[m]}{[s^2]} \\ &= m \cdot \gamma \end{aligned}$$

ANALISI  
DIMENSIONALE

$$[k] = [k_g] [\gamma]$$

$$\gamma = \frac{\Delta v}{\Delta t} \propto \frac{\Delta D}{\Delta t}$$

ANSATZ

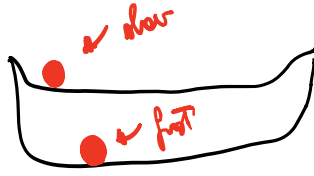
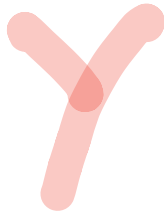
$$k = m \gamma$$

$$U = m \gamma h$$

$$\cancel{m} \gamma h = \frac{1}{2} \cancel{m} \bar{v}_i^2$$

$$\bar{v}_i = \sqrt{2 \gamma h}$$

$v_f$  non dipende da  $\gamma$  ne da  $m$



sempre alle stesse alture

$$\frac{d}{dt} \left( \frac{1}{2} m v^2 + k x \right) =$$
$$= \frac{d}{2} m v \cdot a + k \cdot v = v (m \cdot a + k)$$

$$F = - \frac{d}{dx} (k x) = - \frac{dV}{dx} \Rightarrow \frac{dV}{dx} = \frac{m_1 m_2}{x^2}$$
$$U = \frac{m_2 m_1 G}{R + \delta z} = \frac{m_1 m_2 G}{R} \left( 1 - \frac{\delta z}{R} \right) \Rightarrow \Delta U \approx \delta z m \cdot \frac{MG}{R^2}$$
$$V = \frac{m_1 \cdot m_2}{x}$$

LA SOMMA T+U si CONSERVA

LA QUANTITA' DI MOTO si CONSERVA

COS'ALTRO si CONSERVA?

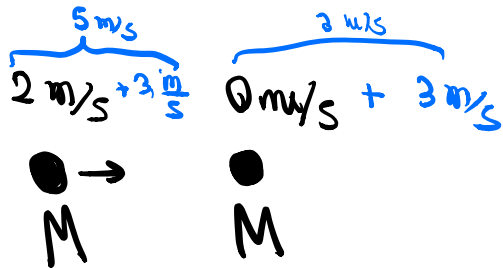
È UNA DOMANDA MOLTO PROFONDA E DARE UNA

RISPOSTA IN GENERALE È ASSAI DIFFICILE

PERO si PUO' STABILIRE UN CRITERIO,

# UNA LEGGE GENERALE

## EX 1



$$P_{in} = v_{in} \cdot M$$

$$P_{out} = M v_1 + M v_2$$

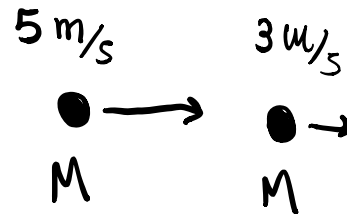
$$K_{in} = \frac{1}{2} M v_{in}^2$$

$$K_{out} = \frac{1}{2} M v_1^2 + \frac{1}{2} M v_2^2$$

$$\begin{cases} \vec{v}_m = \vec{v}_1 + \vec{v}_2 \\ v_m^2 = v_1^2 + v_2^2 \end{cases}$$

$$\begin{cases} \vec{v}_1 = \vec{v}_m - \vec{v}_2 \\ 0 = (-v_m + v_2) v_2 \\ 0 = -2 \vec{v}_m \vec{v}_2 + 2 v_2^2 \end{cases}$$

## EX 2



$$P_{in} = v_m M + v'_m M$$

$$P_{out} = (v_1 + v_2) M$$

$$K_{in} = \frac{1}{2} M (v_m^2 + v'_m{}^2)$$

$$K_{out} = \frac{1}{2} M (v_1^2 + v_2^2)$$

$$\begin{cases} \vec{v}_m + \vec{v}'_m = \vec{v}_1 + \vec{v}_2 \\ v_m^2 + v'_m{}^2 = v_1^2 + v_2^2 \end{cases}$$

$$\begin{cases} \vec{v}_1 = v_m + \overbrace{v'_m}^{v_2} - \vec{v}_2 \\ 0 = 2 v_2^2 + 2 \vec{v}_m \vec{v}'_m - 2 v_2 v_m \end{cases}$$

$$\left\{ \begin{array}{l} \bar{v}_1 = 0 \quad \Delta v_1 = -v_{in} \\ \bar{v}_2 = \bar{v}_{in} \quad \Delta v_2 = v_{in} \end{array} \right.$$

$$-2v_2 v_{in}'$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

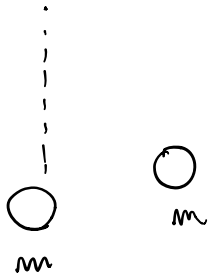
$$v_2 = 2m_3 + 3m_3$$

$$v_1 = 0 m_3 + 3m_3$$

$$v_2 = \frac{(v_{in} + v_{in}') \pm \sqrt{v_{in}^2 + v_{in}'^2 + 2v_{in}v_{in}' - 4v_{in}v_{in}'}}{2}$$

$$= \frac{(v_{in} + v_{in}') \pm (v_{in} - v_{in}')}{2}$$

$$v_2 = \begin{cases} \oplus v_{in} \Rightarrow v_1 = v_{in}' & \Delta v_2 = v_{in} & \Delta v_1 = -v_{in} \\ \ominus v_{in}' \Rightarrow v_1 = v_{in} & \Delta v_2 = 0 & \Delta v_1 = 0 \end{cases}$$



$$\cancel{mv} + \cancel{m \cdot 0} = \cancel{mv_1'} + \cancel{mv_2'}$$

$$v_1' = v - v_2'$$

$$\cancel{mv^2} = \cancel{mv_1'^2} + \cancel{mv_2'^2}$$

$$\cancel{v^2} = \cancel{v^2 + v_2'^2} - 2v\cancel{v_2'} + \cancel{v_2'^2}$$

$$v_2' = v$$

$$v_1' = v - v_2' = 0$$

